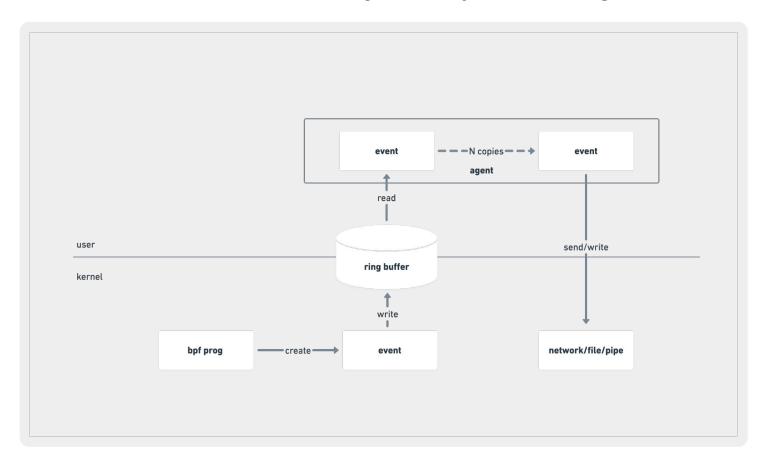
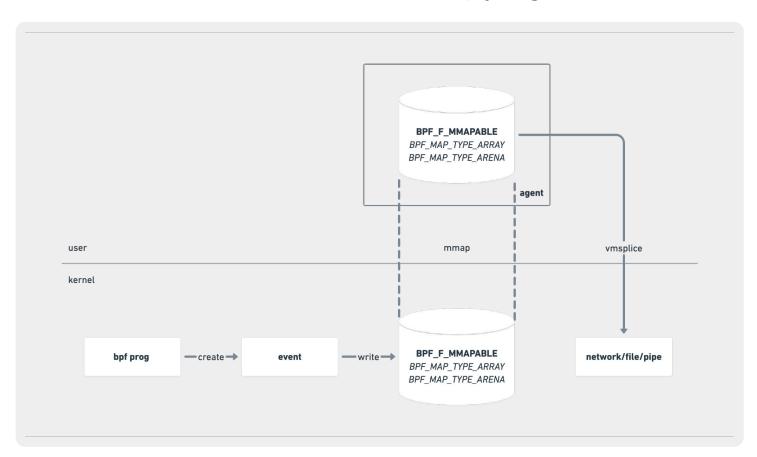
# Splicing BPF maps to the NIC

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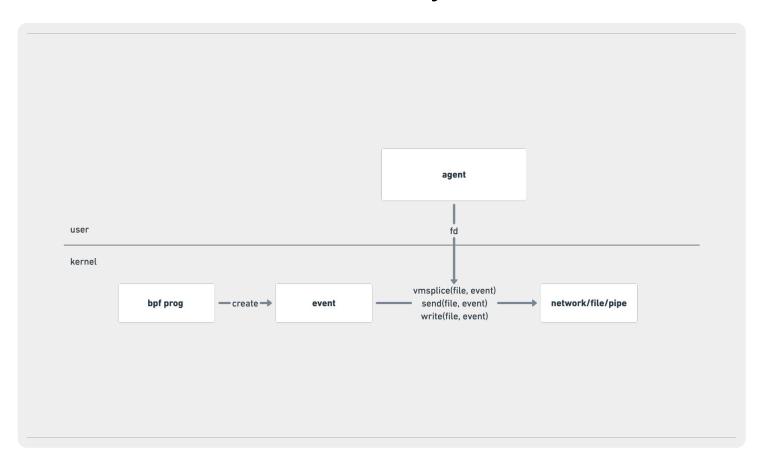
### Case A: events journey in Tetragon



### Case B: less copying



## Case C: low latency BPF events



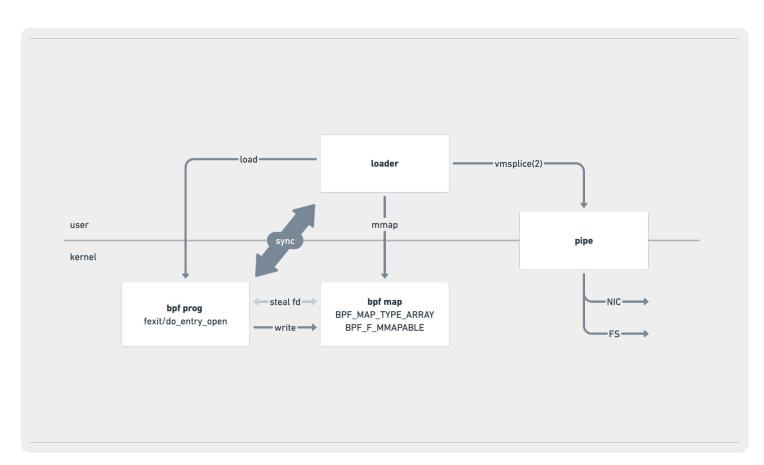
#### Main motivation

- Running without a userspace agent
- No perf ring issues to transmit event/alert between BPF and the agent
- Instant alerting mechanism for low latency
- Less context switch and copies of events

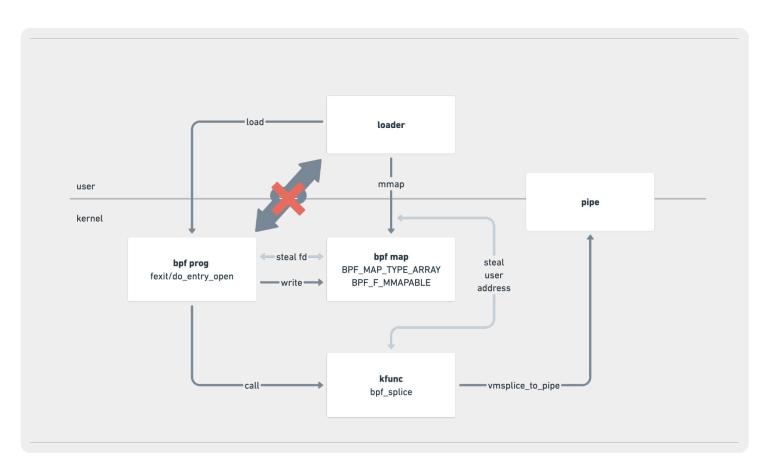
#### Why splice

- We initially thought of splice because it allows for zero copy between kernel and userspace
- Also generic and could be used to wire files/network.
- Splice seems to not be in a very appealing position nowadays (see <u>Rethinking splice()</u>)
- Maybe use io\_uring for async IO from bpf? (see <u>Add bpf for io\_uring</u>, not really related but allowing to run bpf prog from io\_uring events)
- Maybe just start with network send.

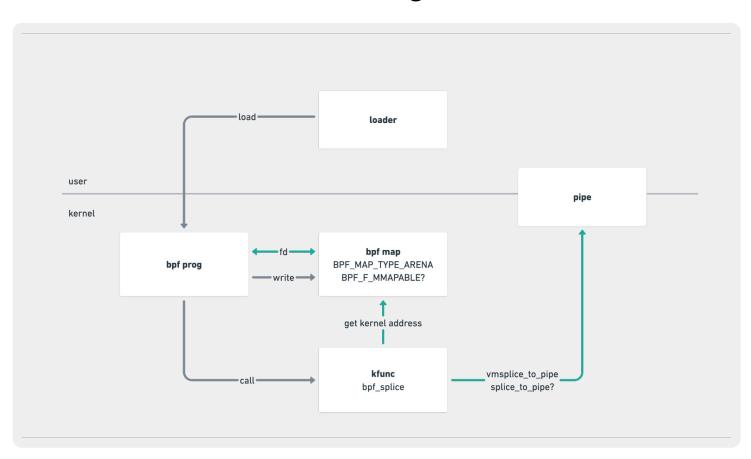
#### PoC B



#### PoC C

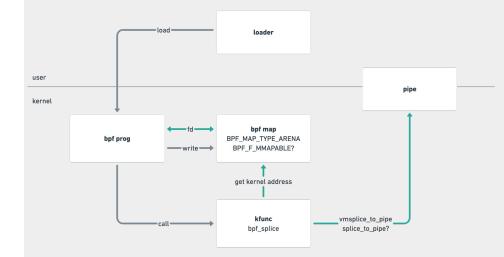


## PoC C goal



#### **Discussions**

- Was this idea already discussed?
- Start with network instead of splice (see <u>Rethinking</u> splice())?
- What kind of interface for passing the fd?
- Benchmark different solutions? What's the benefit of approach C over B?
- IO approach?
  - o sleepable, in kfunc
  - or using io\_uring queues
- Latency (alerting) vs bandwidth (send to a data lake) use-cases:
  - Approach C seems better than B for the latency use-case
- Output format? Could use apache arrow.



#### Kfunc Timer kit [agentless send]

```
int sent:
struct bpf timer *timer; //sleepable timers
int arena *ptr
main() {
 bpf timer set callback(timer, send callback);
 bpf timer start(timer, nsec future, 0);
void send_callback() { // sleepable callback
 ptr = &my bpf map; // arena
 tcp sk = bpf map lookup(&tcp endpoints, 0);
 sent += bpf send(tcp sk, kptr, sizeof(my bpf map));
 bpt timer start(timer, nsec future, 0)
```